Lecture 12: 2nd-order Vector Operators

$$2nd$$
 grad div curl grad \times OK \times Lecture 11 div ∇^2 \times OK \times curl ∇^2 \times OK meaningless

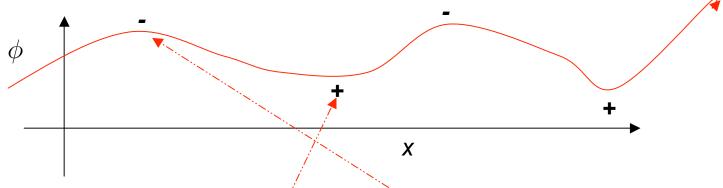
$$\nabla^2 = \vec{\nabla} \cdot \vec{\nabla} \equiv \mathbf{DEL} - \mathbf{SQUARED} \equiv \mathbf{LAPLACIAN}$$

Laplace's Equation $\nabla^2\phi=0$ is one of the most important in physics

ullet For a scalar function (potential) ϕ

$$\nabla^2 = \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}\right) = \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z}\right) \cdot \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z}\right)$$

- is the "second derivative" in 3D, a well-defined scalar function
- Imagine first in 1D



 $\frac{\mathrm{d}^2\phi}{\mathrm{d}x^2}$ = +ve, where curve is concave and -ve, where curve is convex

• If potential is lower than the average value in the surroundings then

$$\frac{d^2\phi}{dx^2}$$
 = +ve, and -ve, when $\phi(x)$ > average in the surroundings

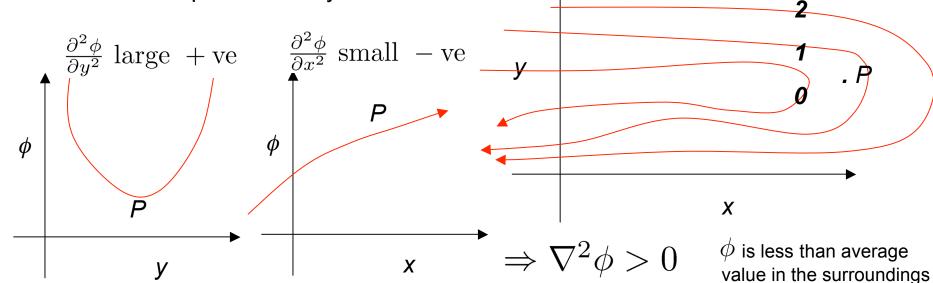
2D Examples

V

X

$$\nabla^2 \phi = \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2}$$

- Local maximum (Q) $\nabla^2 \phi = -\mathrm{ve}$
- Local minimum (P) $\nabla^2 \phi = + ve$
- More complicated behaviour like a steep-sided valley



3D Example

$$\operatorname{div} \vec{E} = \frac{\rho_f}{\epsilon_r \epsilon_0}$$

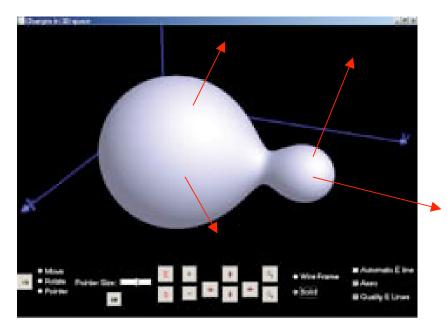
 \vec{E} is conservative $\Rightarrow \vec{E} = -\vec{\nabla}V$

$$\Rightarrow
abla^2 V = rac{-
ho_f}{\epsilon_r \epsilon_0}$$
 Poisson's Equation

Poisson's

in free space
$$\rho_f = 0 \Rightarrow \nabla^2 V = 0$$

Laplace's **Equation**



Equipotential around two unequal charges

 Note that Lapace's Equation implies there are no local maximum or minimum of the potential V

.... but there can be **saddle points**

Laplaces's Equation is very common in physics

Uniqueness Theorem

Given f and (g or h) then V(x, y, z)

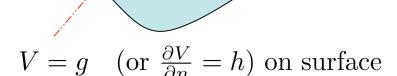
is **UNIQUE**

to within a constant

• Consider two solutions V_1 and V_2 and define

$$\theta = V_1 - V_2 \text{ then } \nabla^2 \theta = \nabla^2 V_1 - \nabla^2 V_2 = f - f = 0$$

- And, on surface $\theta = 0 \text{ or } (\frac{\partial \theta}{\partial n} = 0)$
- To progress further we need to insert θ into **Green's First Theorem**



 $\nabla^2 V = f$ within region

Boundary Condition:

of potential on surface (or on gradient of potential with respect to normal *n* to the surface)

Green's First Theorem

• Apply the *Divergence Theorem* to the vector $\phi \vec{\nabla} \psi$

$$\int dV \vec{\nabla} \cdot (\phi \vec{\nabla} \psi) = \oint d\vec{S} \cdot (\phi \vec{\nabla} \psi)$$

$$\Rightarrow \oint \vec{dS}.(\phi \vec{\nabla} \psi) = \int dV \left[\phi \nabla^2 \psi + (\vec{\nabla} \phi).(\vec{\nabla} \psi) \right]$$

GREEN'S FIRST THEOREM

put
$$\phi = \psi = V_1 - V_2 = \theta \Rightarrow \int_S \theta \frac{\partial \theta}{\partial n} dS = \int_V \left[\theta \nabla^2 \theta + (\vec{\nabla} \theta)^2 \right] dV$$

• One of these two is zero on surface, and this is zero

$$\Rightarrow \int_{V} (\vec{\nabla}\theta)^2 dV = 0 \Rightarrow \vec{\nabla}\theta = 0 \Rightarrow \theta = \text{constant or } V_1 - V_2 \text{ is a constant}$$

• $V_1 = V_2$ throughout volume if $V_1 = V_2$ on the surface; the uniqueness theorem

Other Possible Combinations

grad div

$$\vec{\nabla}(\vec{\nabla}.\vec{A}) = \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z}\right) \left[\frac{\partial A_x}{\partial x} + \frac{\partial A_y}{\partial y} + \frac{\partial A_z}{\partial z}\right]$$

$$= \left(\frac{\partial^2 A_x}{\partial x^2} + \frac{\partial^2 A_y}{\partial x \partial y} + \frac{\partial^2 A_z}{\partial x \partial z}, \frac{\partial^2 A_x}{\partial y \partial x} + \frac{\partial^2 A_y}{\partial y^2} + \frac{\partial^2 A_z}{\partial y \partial z}, \frac{\partial^2 A_x}{\partial z \partial x} + \frac{\partial^2 A_y}{\partial z \partial y} + \frac{\partial^2 A_z}{\partial z^2},\right)$$

$$\neq \vec{\nabla}^2 (A_x, A_y, A_z) \equiv (\nabla^2 A_x, \nabla^2 A_y, \nabla^2 A_z)$$

curl curl

$$\vec{\nabla} \times (\vec{\nabla} \times \vec{A}) = \vec{\nabla}(\vec{\nabla} \cdot \vec{A}) - \vec{\nabla^2} \vec{A}$$

which is not necessarily zero: we will prove this equation in Lecture 14